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## The Contents of Case 10610960

Qnum	Query	DB Name	Thesaurus	Operator	Plural
Q1	internal	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q2	Q1 same target	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q3	external or surface	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q4	Q1 same Q2 same Q3 Q4 same (correlation or correlating or correlat\$4 or match\$4 or matching or matched)	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q5	600/\$.ccls.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q6	606/130.ccls.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q7	Q6 or Q7	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q8	Q5 and Q8	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q9	606/130.ccls.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q10	articulated same arm surgical or probe or catheter or instrument	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q11	target	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q12	robot	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q13	Q12 same Q13	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q14	Q11 same Q15	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q15	Q10 and Q16 Q16 and (robot or robotic or automatic) Q18 and (robot or robotic)	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q16	600/429.ccls.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q17	Q11 and Q20 (robot or robotic)	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q18	600/429.ccls.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q19	Q11 and Q20 (robot or robotic)	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q20	600/429.ccls.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q21	Q11 and Q20 (robot or robotic)	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES
Q22	600/429.ccls.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD	ASSIGNEE	ADJ	YES

Q23	Q21 and Q22	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q24	Q13 and Q23	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
	changing			
Q25	same viewing sama trajectory Q22 same (correcting or	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q26	correction) same trajectory	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q27	Q20 and Q26	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q28	Q7 and Q22	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
	Q28 and			
Q29	(target same trajectory) intervening	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q30	same view same target	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q31	Q30 and smith	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q32	6064904.uref.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q33	virtual and smith	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q34	Q20 and Q33	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q35	Ferre.inv.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q36	Q20 and Q35	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q37	Q17 and deviation deviation	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q38	same trajectory	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q39	Q11 same Q38	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q40	"Van Der Burg"	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q41	Q40 and Q11	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q42	Q40 and robot	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
	Van same			
Q43	Der same Brug	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q44	Q43 and Q11	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q45	5817105.pn.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q46	6112113.pn.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q47	Van Der Brug.inv.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q48	glassman.inv.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q49	Q48 and	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES